



Bilkent University

Risk-Averse Airline Revenue Management with Coherent Measures of Risk

Recep Yusuf Bekci

Proposal

Outline

1. Problem Definition
2. Risk Neutral Model
3. Risk Averse Model
4. References

Revenue Management

- Airline Industry
- Overbooking
- No-shows

Risk Neutral Model

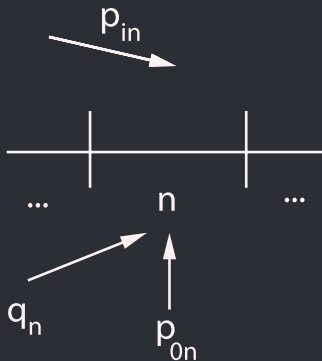
We need to divide the time horizon into discrete periods.



Risk Neutral Model

In each period, there can be three events:

- p_{ni} is the probability of a request for a seat in class i .
- q_n is the probability of cancellation.
- p_{0n} is the probability of a null event.



Risk Neutral Model

If a request is accepted for class i at stage n , $r_{in} \geq 0$ is the amount of earned revenue.

We have

$$\sum_{i=1}^m p_{ni} + q_n + p_{0n} = 1 \quad \text{for all } n \geq 1.$$

Risk Neutral Model

We also have no-shows. Each customer has a probability β of no-show at the departure time. x is the state.

Definition

$Y(x)$: number of customers show up at stage 0.

$Y(x) \sim \text{Binomial}(x, 1 - \beta)$. Let $Y(x) = y$ at the time of departure.

Definition

$\pi(y)$: overbooking penalty function.

Risk Neutral Model

Definition

$U_n(x)$ is the maximum expected revenue over periods n to 0.

At period 0,

$$U_0(x) = E[-\pi(Y(x))], \quad 0 \leq x < N$$

We have recursive function as

$$U_n(x) = \sum_{i=1}^m p_{in} \max\{r_{in} + U_{n-1}(x+1), U_{n-1}(x)\} \\ + q_n U_{n-1}(x-1) + p_{0n} U_{n-1}(x)$$

Risk Neutral Model

Booking Limit Policy

In order to define a control limit policy we need to show that

$U_n(x) - U_n(x + 1)$ is **nondecreasing** in $x = 0, 1, \dots, N - n - 1$.

We use the following lemmas.

Lemma 1 Let $f(y)$, $y \geq 0$, be a nondecreasing convex function. For each non-negative integer x , let $Y(x)$ be a binomial (x, γ) random variable ($0 < \gamma < 1$) and let $h(x) = E[f(Y(x))]$. Then $h(x)$ is nondecreasing convex in $x \in \{0, 1, \dots\}$.

Lemma 1 has been proved by Shaked and Shanthikumar (1994).

Risk Neutral Model

Booking Limit Policy

Lemma 2 Let $p_{0n} = \bar{q}_n - q_n$ where \bar{q}_n stands for $1 - \sum_{i=1}^m p_{in}$. Let $H(x) = q_n U_{n-1}(x-1) + (\bar{q}_n - q_n) U_{n-1}(x)$. If $U_n(x)$ is a nonincreasing concave function in x then $H(x)$ is a nonincreasing concave function in x .

Lemma 3 Let $r_{in} \geq 0$ is fixed and $g(x) = \max\{r_{in} + U_{n-1}(x+1), U_{n-1}(x)\}$. If $U_{n-1}(x)$ is concave and nonincreasing, then $g(x)$ is concave and nonincreasing.

Lemma 2 and **Lemma 3** have been proved by Lippman and Stidham (1977).

Risk Neutral Model

Booking Limit Policy

$U_n(x) - U_n(x + 1)$ can be seen as opportunity cost of accepting a request at stage $n + 1$. Let b_{in} be the booking limit at stage n and class i . It is defined as,

$$b_{in} := \min\{x : U_{n-1}(x) - U_{n-1}(x + 1) > r_{in}\}$$

Risk Neutral Model

Booking Limit Policy

After all, our booking limit policy is the following,

accept a request for fare class i in state x at stage n

$$\Leftrightarrow 0 \leq x < b_{in}.$$

- We will show whether a control limit policy exists for risk-averse model with coherent measures of risk.

Risk Averse Model

Let $\rho(\cdot)$ be a coherent risk measure. Using first order mean semi-deviation representation as the coherent risk measure we have following dynamic programming equations.

$$V_0(x) = \mathbb{E}[-\pi(Y(x))] - \kappa \mathbb{E} \left[\mathbb{E}[-\pi(Y(x))] + \pi(Y(x)) \right]_+$$

$$V_n(x) = \mu_n - \kappa \left[\sum_{i=1}^m p_{ni} [\mu_n - \max\{V_{n-1}(x+1) + r_{in}, V_{n-1}(x)\}]_+ \right. \\ \left. + q_n [\mu_n - V_{n-1}(x-1)]_+ + p_{0n} [\mu_n - V_{n-1}(x)]_+ \right]$$

Risk Averse Model

Where;

- $\kappa \in [0, 1]$
- $\mu_n = \sum_{i=1}^m p_{ni} \max\{V_{n-1}(x+1) + r_{in}, V_{n-1}(x)\} + q_n V_{n-1}(x-1) + p_{0n} V_{n-1}(x)$

Risk Averse Model

Dual Representation

It is very hard to show that $V_n(x)$ is concave and nonincreasing. So, we will use the dual representation.

Let Y be a random reward. Then, dual representation of $\rho(\cdot)$ is

$$\rho(Y) = \min_{\eta \in \mathcal{A}} \mathbb{E}_{\eta}[Y]$$

(Artzner et al. (1999))

Risk Averse Model

Dual Representation

Then, dual representation of mean semi-deviation,

$$V_0(x) = \min_{\eta \in A_0} \mathbb{E}_\eta[-\pi(Y(x))]$$

$$V_n(x) = \min_{\eta \in A_n} \sum_{i=1}^m \eta_i \max\{V_{n-1}(x+1) + r_{in}, V_{n-1}(x)\} \\ + \eta_{m+1} V_{n-1}(x-1) + \eta_{m+2} V_{n-1}(x)$$

References I

- [1] M. Shaked AND J. G. Shanthikumar, Stochastic Orders and Their Applications. Academic Press, San Diego, California, 1994.
- [2] Lippman, Steven A., and Shaler Stidham Jr. "Individual versus social optimization in exponential congestion systems." Operations Research 25.2 (1977): 233-247.
- [3] Subramanian, Janakiram, Shaler Stidham, and Conrad J. Lautenbacher. "Airline Yield Management with Overbooking, Cancellations, and No-Shows." Transportation Science 33.2 (1999): 147-67.
- [4] Aydın, Nurşen, S. Ilker Birbil, J. B. G. Frenk, and Nilay Noyan. "Single-Leg Airline Revenue Management with Overbooking." Transportation Science 47.4 (2013): 560-83.

References II

- [5] Artzner, Philippe, F. Delbaen, J.M. Eber and D. Heath. "Coherent Measures of Risk.", *Mathematical Finance* 9.4 (1999): 203-228.